WEEK 3



# Physics of Engineer Chapter 3: Motion

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**PR** 

### Topic 1.2: 1-2 Motion Dimensions.

• One Motion Dimension



• Two Motion Dimension







### Let's look at the pictures on next page !





### **Distance:** How far did the point move ?



<sup>4</sup> (Guide: Think of the cheetah's stride, the runner's lap, the apple's drop.)





### Velocity: How fast did the point move ?



<sup>5</sup> (Guide: The cheetah's blur, the runner's pace, the apple's plummet.)





### Acceleration: How quickly did the point change its speed ?



6 (Guide: The cheetah's burst, the runner's final push, the apple's slowing fall.)

**Displacement:** The total change in position.







Velocity: The rate of change of position





Acceleration: The rate of change of velocity







**Displacement**  $(\Delta x)$ : The change in position, measured in meters (m).

 $\Delta X = X_2 - X_1$ 

(where  $\Delta x$  is displacement,  $x_2$  is final position, and  $x_1$  is initial position)



### One Dimension Motion : Example

A runner crosses the finish line 100 meters from the starting point.



Solution: Their displacement is  $\Delta x = 100$ m.



### One Dimension Motion : Example

The runner finishes the 100m race in 10 seconds.





Solution: Their average velocity is v = 100m / 10s

= 10m/s.





### One Dimension Motion : Example

The runner starts from rest and reaches their 10m/s velocity in 2 seconds.



Photo: https://www.dreamstime.com/photos-images/running-woman-runner-speed-motion-composite.html

Solution: Their acceleration is a = (10m/s - 0m/s) / 2s

 $= 5 \text{m/s}^2$ .

**Velocity** (v): The rate of change of displacement, measured in meters per second (m/s).

 $\vee = \Delta \times / \Delta t$ 

(velocity equals displacement divided by time)

(where v is velocity,  $\Delta x$  is displacement, and  $\Delta t$  is time)





Acceleration (a): The rate of change of velocity, measured in meters per second squared (m/s<sup>2</sup>).

 $a = \Delta v / \Delta t$ 

(acceleration equals change in velocity divided by time)

(where a is acceleration,  $\Delta v$  is change in velocity, and  $\Delta t$  is time)



Equations for specific cases:

 $\vee = \vee_0 + at$ 

(final velocity equals initial velocity plus acceleration times time).



Equations for specific cases:

 $\Delta x = v_0 t + 1/2at^2$ 

(displacement equals initial velocity times time plus half of acceleration times time squared).

Applications:Projectilemotion(throwing a ball), braking distance of<br/>vehicles.





### Let's look at the pictures on next page !







Position of an object defined by two independent coordinates:

- X: Horizontal distance
- Y: Vertical distance





Position of an object defined by two independent coordinates:

- X: Horizontal distance
- Y: Vertical distance





The familiar characters return:

Displacement ( $\Delta x$ ,  $\Delta y$ ):

- Change in position in the X and Y directions.
- Measured in meters (m).
- Equation:  $\Delta x = x_2 x_1$ ,  $\Delta y = y_2 y_1$





The familiar characters return:

Velocity  $(v_x, v_y)$ :

- Rate of change of displacement in X and Y directions.
- Measured in meters per second (m/s).
- Equation:  $v_x = \Delta x / \Delta t$ ,  $v_y = \Delta y / \Delta t$





The familiar characters return:

Acceleration (a<sub>x</sub>, a<sub>y</sub>):

- Rate of change of velocity in X and Y directions.
- Measured in meters per second squared (m/s<sup>2</sup>).

• Equation: 
$$a_x = \Delta v_x / \Delta t$$
,  $a_y = \Delta v_y / \Delta t$ 



Real Life Example: Projectile Motion.

#### Equations:

Time of flight (T):  $T = 2v_0 \sin\theta/g$ Maximum height (H):  $H = v_0^2 \sin^2\theta/2g$ Range (R):  $R = v_0^2 \sin 2\theta/g$ 



Real Life Example: Circular Motion.

Centripetal Acceleration  $(a_c)$ :

- Acceleration towards the center of the circle.
- Equation:  $ac = \sqrt{2}/r$

Centripetal Force  $(F_c)$ :

- Force causing circular motion.
- Equation:  $F_c = ma_c = mv^2/r$



Real Life Example: Relative Motion.

Relative Velocity (v<sub>rel</sub>):

- Velocity of one object relative to another.
- Equation:  $v_{rel} = v_1 v_2$  (for objects moving in opposite directions)





Distance (d)

**Distance**: Combining X and Y

displacements using Pythagorean theorem

Equation:  $d = \sqrt{(\Delta x^2 + \Delta y^2)}$ 



Photo:https://www.istockphoto.com/th/%E0%B8%A0%E0%B8%B2%E0%B8%96%E0%B9%88%E0%B8%B2%E0%B8%A2/physics-chalkboard



Velocity (v)

**Velocity:** Adding individual X and Y velocities as vectors

Equation: 
$$\vee = \sqrt{(\vee x^2 + \vee y^2)}$$



Photo:https://www.istockphoto.com/th/%E0%B8%A0%E0%B8%B2%E0%B8%96%E0%B9%88%E0%B8%B2%E0%B8%A2/physics-chalkboard



Acceleration (a)

Acceleration: Calculating the rate of change of both velocities



Photo:https://www.istockphoto.com/th/%E0%B8%A0%E0%B8%B2%E0%B8%96%E0%B9%88%E0%B8%B2%E0%B8%A2/physics-chalkboard



## The Journey Continues: Delving Deeper



Further exploration awaits:

- Projectile motion equations
- Circular motion formulas
- Relative motion principles

- Our journey through one-two dimensional motion has unveiled a captivating world!
- From soaring birds to orbiting planets, every movement tells a story governed by fascinating principles.
  Remember, physics isn't just about
  - equations; it's about appreciating the elegance and beauty of how our universe moves.
- ✓ Keep exploring, keep questioning, and keep unveiling the secrets of motion!



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# Physics of Engineer Chapter 1: Motion

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